

Gliding Motility in Bacteria: Insights from Studies of *Myxococcus xanthus*

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INTRODUCTION

Motility is arguably the most impressive feature of a microbe's physiology. Active movement ultimately uncovered microbes as living organisms to the first microscopic inspection by Antonie van Leeuwenhoek more than 300 years ago (31) and since this time has attracted the curiosity of innumerable scientists. In general, motile prokaryotic microorganisms move in aqueous environments by swimming or by control of buoyancy or along surfaces by using distinct modes of surface translocation. Most research has focused on understanding swimming motility in prokaryotes. Fundamental insights have been gained from thorough studies of the molecular architecture of the flagellum, from the energy transduction mechanism and mode of force generation, and from the control of motility, all of which serve now as paradigms for motility in biology (for a review, see reference 14). Notably, as shown by Waterbury et al. for a cyanobacterium (128), not all swimming bacteria are flagellated. Swimming motility is advantageous only for microorganisms living in aqueous habitats. Many microbes, however, live in environments with a low water content or changing humidity. These environments include biofilms, microbial mats, and soil, where the exploration of a new food source by means of swimming motility is unfeasible. These organisms are faced with the challenge of how to move on surfaces that are covered with only a few layers of water molecules. One solu-

tion of some swimming bacteria is to produce excessive lateral flagella that enable them to swarm in a thin fluid layer on a solid surface (for a review, see reference 46). However, many other prokaryotes employ one of the two modes of active cell translocation on a solid surface: gliding or twitching.

Historically, gliding is defined as the movement of a non-flagellated cell in the direction of its long axis on a surface (51). This rather broad definition, which does not specify a molecular apparatus or a mode of force generation, has therefore been used to describe movements by many phylogenetically unrelated bacteria (Fig. 1). As will be shown in this review, gliding movement can be generated by fundamentally different molecular mechanisms that can operate simultaneously even in a single microorganism. Consequently, use of the term "gliding" should not be considered to imply the operation of a specific motility mechanism. Several models for gliding have been proposed for different organisms to explain the seemingly smooth advancement of cells on solid surfaces. These models include operation of contractile elements (22), directional propagation of waves along the cell surface (60), directional extrusion of slime (59, 99), rotary motors (91), controlled release of surfactants from poles of cells (34, 67), and movement of adhesion sites in the outer membrane along tracks fixed to the peptidoglycan of the cell wall (72). In most cases, the models were postulated as a result of observations on motility behavior of single cells. However, to date, no model has been verified by biochemical, molecular, and ultrastructural studies, and it seems unlikely that all gliding bacteria harbor the same motility mechanism. The focus of this review is on recent research which seeks to provide a mechanistic and molecular understanding for gliding. The single-cell gliding bacteria

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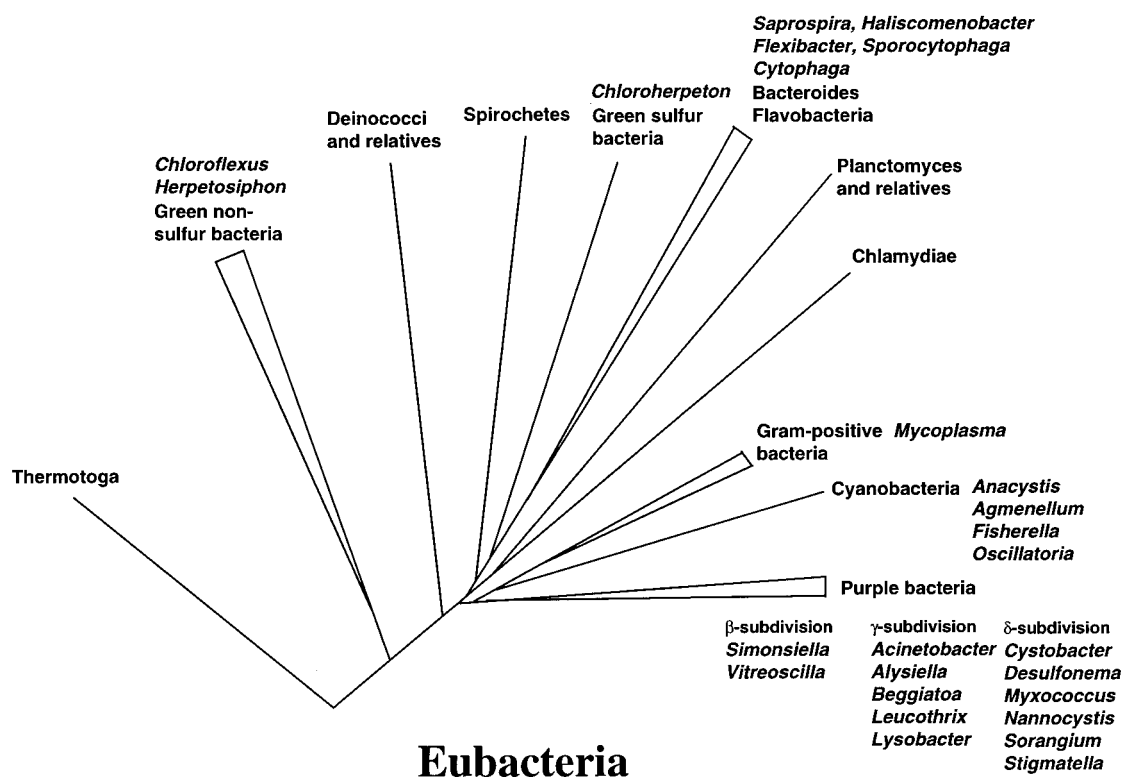


FIG. 1. Occurrence of gliding bacteria among the eubacteria. The figure depicts examples of bacteria (indicated in italics) that have been reported to move by "gliding." Note that "gliding" is an operational definition, and not all bacteria may glide by the same mechanism. No gliding archaea have been reported. Modified from reference 58.

Myxococcus xanthus, *Flavobacterium*, and *Cytophaga* strain U67, as well as the filamentous organism *Flexibacter polymorphus*, serve as model organisms in these studies. Interestingly, gliding motility has so far not been reported for archaea. Diversity and ecological aspects of gliding motility have been reviewed recently (95, 96).

GLIDING MOTILITY IN *MYXOCOCCUS XANTHUS*

Most of the research on gliding motility has been conducted with *M. xanthus* (50, 127, 143, 145). This microorganism is a Gram-negative soil bacterium which belongs to the delta subdivision of proteobacteria and is specialized to mineralize insoluble organic matter, specifically proteins (33, 95, 104). In common with other myxobacteria, *M. xanthus* exhibits an unusually complex life cycle during which gliding motility plays a crucial role (110). Under vegetative conditions, cells move as coordinated swarms. These swarms may contain thousands of cells, which secrete hydrolytic enzymes into their environment that lyse other cells and convert insoluble proteins into soluble, transportable amino acids. Metabolism of these amino acids and other compounds is strictly aerobic. The feeding strategy of moving in swarms on the metabolizable substrate has been termed the "wolf pack" effect to reflect the fact that large numbers of organized cells undoubtedly utilize insoluble nutrients more efficiently than a single cell (104). Furthermore, coordination of vegetative cells in swarms provides the basis for survival when nutrients become limiting. When cells are starved of nutrients, tens of thousands aggregate to form a fruiting body, within which cells differentiate into spores. The organized movement of vegetative cells ensures that sufficient

cells are present to form this fruiting body. Subsequent dispersal of mature, spore-containing fruiting bodies guarantees that after spore germination, cells are present at a sufficiently high density to allow the formation of new vegetative swarms. It is therefore apparent that the motility of *M. xanthus* is a crucial prerequisite for this lifestyle and thus has attracted much research effort.

Over the few past decades, research has focused on genetic and molecular approaches, as well as on high-resolution motion analyses, to develop a cellular and mechanistic understanding of gliding motility in *M. xanthus*. Hodgkin and Kaiser initiated a genetic analysis by screening chemical- and UV-induced mutants for visible defects in colony swarming (56, 57). Subsequent analysis of these mutants revealed that motility in *M. xanthus* is controlled by two multigene systems: the A (adventurous) system, which controls gliding motility of individual, isolated cells, and the S (social) motility system, which is essential for cell movement in swarms and during aggregation and fruiting-body formation (56, 57). Both motility systems are required for wild-type swarming, because swarming is completely abolished in any A⁻ S⁻ double mutant. It should be noted that although gliding of isolated cells is observed only in A⁺ cells, cells in swarms can move by either A motility or S motility or by both systems at a time. The use of single-cell observations to infer involvement of a specific type of motility system can be misleading, and in a strict sense, A motility and S motility are defined only by the macroscopically visible non-swarming phenotype of a double-mutant colony (56).

As a result of significant progress in recent years, a refined picture of how *M. xanthus* moves is becoming apparent. Experimental evidence that is reviewed below suggests that A and

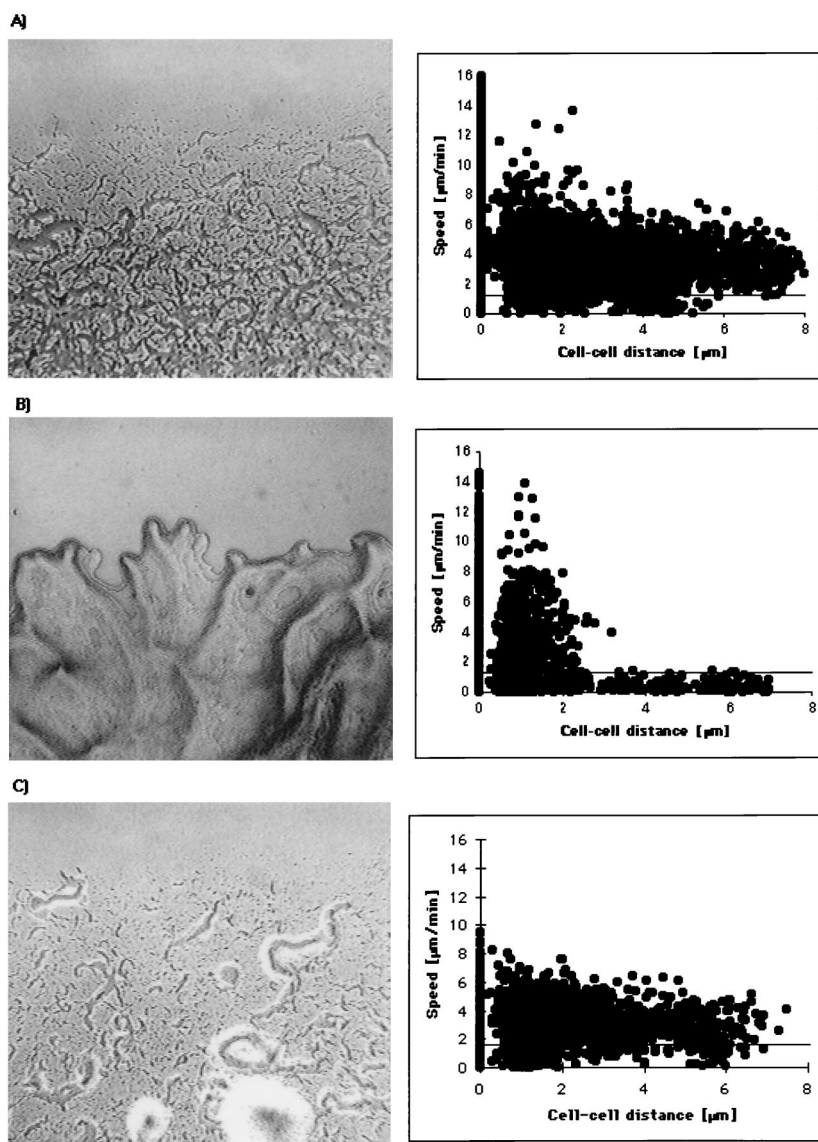


FIG. 2. Two gliding motility systems are operative in *M. xanthus*. (Left) Colony morphology. (Right) Gliding speed plotted against cell-cell distance of individual cells (the detection limit for active movement was 1 $\mu\text{m}/\text{min}$ [117]). (A) Wild-type DK1622 (A^+S^+). Gliding-speed data are from reference 117. (B) JZ315 (*cglB*, A^+S^-). Gliding-speed data are from reference 101. Note that when the cells were separated by more than 2 μm , no active single-cell movement was observed. When the cells were in contact, the velocities observed were similar to those found when wild-type cells moved in close proximity (A). (C) DK3473 (*pilR*, A^+S^-); cell movement of 50 individual DK3473 cells was examined as described previously (117). A total of 4,531 speed and cell-cell distance values were obtained and plotted. The speed of isolated cells was similar to that of wild-type cells. However, cells did not exhibit high-speed movements, as observed for wild-type and *cglB* cells (A and B) when in close proximity.

S motility do not represent different modes of a single gliding mechanism but, instead, comprise two distinct motility mechanisms: pilus-independent single-cell gliding (A motility) and pilus-dependent movements (S motility), which may be related to another surface translocation mechanism, called twitching. Twitching is described as intermittent, jerky cell movement that seems to lack the degree of organization seen in gliding. Twitching, unlike S motility, can occur in directions other than the long axis of the cell (53). However, functional type IV pili are essential for both twitching motility and S motility. Genes of the S system have recently been shown to include genes necessary for the synthesis, processing, export, assembly, and function of type IV pili (102, 125, 139–141).

Gliding of *M. xanthus* Cells as Single Cells or in Swarms

In this section, observations on the movement of wild-type swarms and on isolated single cells are summarized. Colonies of wild-type *M. xanthus* (DK1622, DZ2) expand as flat swarms on a 1.5% agar surface (Fig. 2A). Microscopy at the edges of these swarms shows that the advancing front of the swarm is composed predominantly of individual cells, with groups of cells forming behind (56) (Fig. 2A). The rate of swarm expansion depends on cell density in a type of first-order kinetics with a maximal rate of approximately 1.6 $\mu\text{m}/\text{min}$ and a half-saturation cell density of approximately 2×10^8 cells per ml (62). The swarming rate also depends on the concentration of

the agar support (57). When the rate is measured as the expansion of a colony area, swarming appears to be faster on 0.4% agar and drops to about 1/10 the efficiency when the agar concentration increases to 2% (107). *M. xanthus* colonies also respond to stress forces in the (agar) surface, a phenomenon called elasticotaxis (37, 119). Small compressions in the agar surface lead *M. xanthus* colonies to swarm preferentially in the direction perpendicular to the stress force, which results in an elongated elliptical colony (37).

Videomicroscopy motion analyses have been used to determine the rates at which individual isolated cells glide on a 1.5% agar surface. The studies showed that the translocation velocity is highly variable for a given cell but also varies between different cells (117). Most cells were found to move at velocities between 1.5 and 6 $\mu\text{m}/\text{min}$, although occasionally speeds of up to 20 $\mu\text{m}/\text{min}$ were observed (117). Cells change the direction of movement by reversing every 5 to 7 min, so that the leading end becomes the lagging end (12, 118). Bending of the highly flexible cell body during movement frequently results in deviations from the original track of less than 90° , thus also contributing to directional changes. Individual *M. xanthus* cells do not have a preferred direction of movement; i.e., a cell does not have a "head or tail" (106, 118). This is indicated by measurements of cellular gliding velocity taken in both the forward and backward directions, as well as by studies that timed the duration of movement in one or the other direction. Gliding speed is also independent of cell length. When *M. xanthus* cells were treated with cephalaxin, which increases the cell length to up to 20 μm (compared to 6 μm untreated), no difference in gliding speed compared to untreated cells was noticeable (118a), suggesting that the gliding motor(s) operates at constant speed. Interestingly, the translocation velocity of individual cells varied with cell-cell distance (117) (Fig. 2A). When individual cells were separated by more than one cell diameter (0.5 μm) from the nearest neighbor, they moved with an average velocity of 3.8 $\mu\text{m}/\text{min}$. However, in close proximity, cells moved with an average velocity of 5.0 $\mu\text{m}/\text{min}$ (117). These kinetically distinguishable modes of single-cell gliding can be separated genetically into A- and S-motility-related movements, respectively (Fig. 2B and C).

On rare occasions, individual wild-type cells have been observed to glide while one cell pole is fortuitously fixed on an agar surface. This event results in flexing of the cell as the end which is not fixed glides backward and forward (118). Long cells have also been observed to bend into a "U" and to move in one direction in this configuration. Because the cell poles would move away from each other if the cell was not a bent "U," this observation suggests that each cell pole can move independently in both directions. In addition, the region between the poles can exhibit movement, indicating that the subcellular elements that promote motility are localized at both cell poles and along the length of the cell body (117) (Fig. 3). Therefore, *M. xanthus* cells are proposed to contain not one single gliding motor which is localized to a specific site but, instead, multiple motor elements positioned along the entire cell surface (117) (Fig. 3). The activities of these multiple motor elements would normally be coordinated to generate overall movement in either the forward or the reverse direction. Currently, no data are available to differentiate between the possibility that cells (i) contain a single set of motor elements where each element is capable of operating in both directions or (ii) contain two sets of unidirectional motors that are arranged opposite to each other and differentially regulated (Fig. 3).

Under certain conditions, *M. xanthus* cells have also been found to bend in the absence of any translocation of the cell

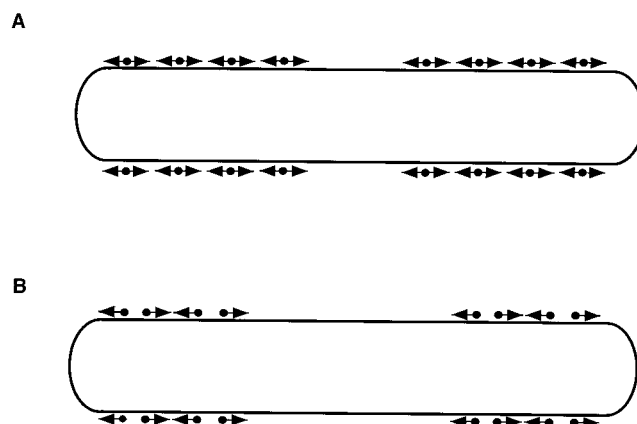


FIG. 3. Models for localization of motility elements on the surface of *M. xanthus* cells. Multiple motor units are located along the cell body. (A) In this model, a single motor unit can generate displacement in two directions that are opposite to each other (\leftrightarrow). (B) In this model, two types of unidirectional motors exist (\rightarrow and \leftarrow), each capable of generating force in only one direction. The motor elements are arranged opposite each other, so that selected activation of one or the other results in movement in one or the other direction.

body. Such bending was observed when *dsp* cells (see below) attached to nitrocellulose-coated coverslips (Fig. 4). While the majority of the cell body did not show any displacement, the ends of individual cells were found to flex until a certain degree of bending was achieved, when the end would "snap back" to form a straight cell. The flexing proceeded at a rate similar to that of gliding. These observations suggest that force can be generated relative to distal body sections in the absence of translocation of the entire cell.

In contrast to other gliding bacteria, such as *Cytophaga*, *M. xanthus* cells have not been reported to rotate during translocation. However, cells have been observed to pivot around one cell pole which is tethered to a surface in a wet mount. Similar to studies with other gliding bacteria (72, 91), movement of beads along the surface of a cell has been examined in *M. xanthus* (118a). It appears that the direction of a moving bead does not always correlate with the direction of cell gliding. While a cell is moving forward, beads may be moving forward, backward, or not at all. Bead movement was also observed on cells which were not moving. Two beads on the surface of a single cell could be found to move in opposite directions. These observations are very similar to those made previously by Lapidus and Berg with *Cytophaga* strain U67 (72). Beads frequently seem to become "trapped" at cell poles. The velocity of bead movement is on the order of 2 to 4 $\mu\text{m}/\text{min}$ (118a), which is comparable to the velocity of individual gliding cells, suggesting that bead movement along the cell surface may be related to gliding movement (72).

No study that identifies a source of energy for gliding movement in *M. xanthus* has been reported. The electrochemical membrane potential was proposed to power gliding motility in *Flexibacter* (see below). Because two gliding mechanisms operate in *M. xanthus*, each mechanism may utilize a different energy source (e.g., ATP versus electrochemical ion potential), thus complicating bioenergetic studies.

Subcellular Structures with Proposed Roles in Motility

Several subcellular structures in *M. xanthus* are believed to be involved in promoting cell movement: (i) periodic chain-like structures associated with the outer membrane (38, 75) and (ii) polar type IV pili (61, 79).

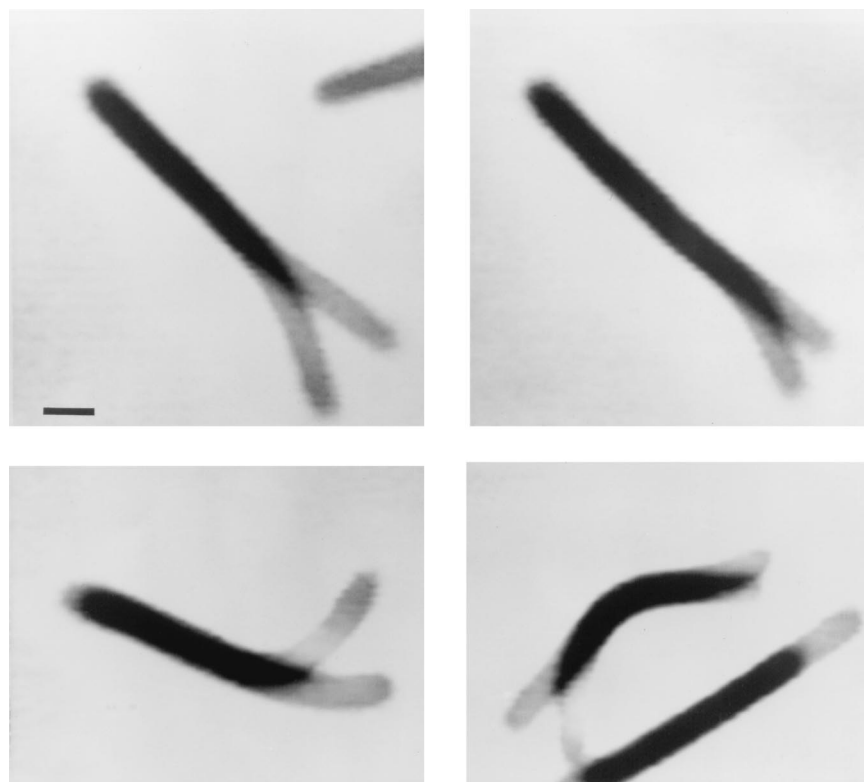


FIG. 4. Flexing of an *M. xanthus* cell. Cells of DK1680 (*dsp*) were grown in CTT liquid medium (117) to a density of about Klett 100 ($\sim 5 \times 10^8$ cells/ml), and 10- μ l drops were placed on nitrocellulose-coated coverslips. Cell movement was monitored under an inverted microscope, and images were recorded during the observation period. In the absence of net movement, cells were observed to flex. This can be easily shown when superimposing two images that were recorded at different times. Dark areas indicate overlap of the cell during both recordings, and lighter areas show displacement of cell sections. The time difference between the two superimposed images was 1 min 48 s for the picture at top left (size bar included), 1 min 10 s for the picture at bottom left, 7 s for the picture at top right, and 27 s for the picture at bottom right. In the last picture, the lower cell was gliding in direction of the long axis of the cell while the upper cell flexed. Bar, 0.5 μ m.

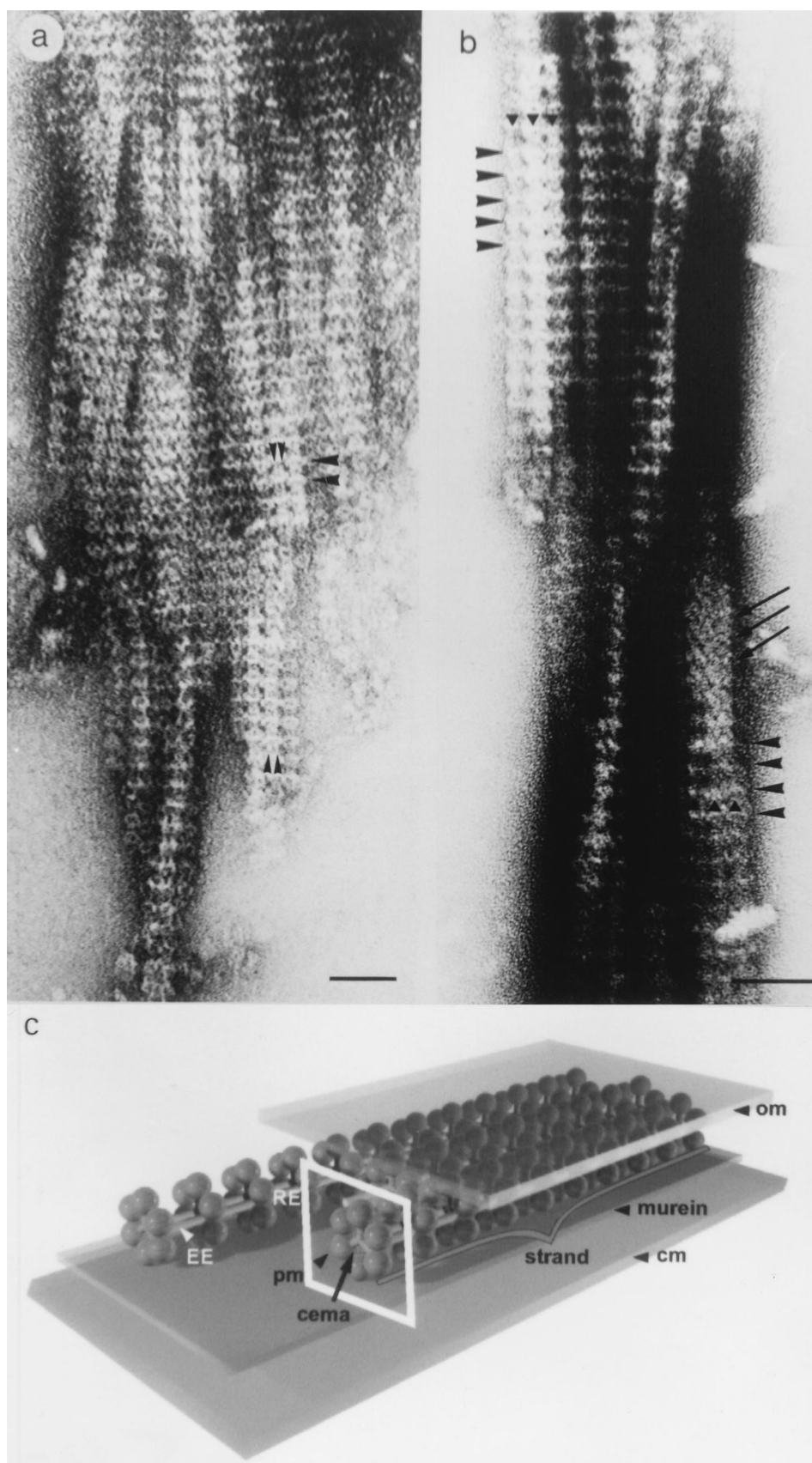
Chain-like structures. Reichenbach and coworkers conducted detailed electron microscopy studies with whole cells and subcellular fractions of the gliding myxobacteria *Myxococcus fulvus* and *M. xanthus* (strains Mx f65-9 and DK1622). In both organisms, similar structures that are believed to be components of the gliding apparatus were identified (Fig. 5) (38, 75). The basic elements of this proposed gliding apparatus in *M. xanthus* DK1622 are linear chain-like strands. These strands are composed of multiple ring-like structures, which are threaded evenly along elongated elements (Fig. 5). Each ring element in a strand has an average outer diameter of about 16.4 nm and is composed of six or more peripheral protein masses and possibly three small central masses. The rings are connected to each other by two parallel strings of filamentous proteins, the elongated elements, which attach at the inner side of a ring. They separate two neighboring rings evenly at a distance of about 15.5 nm. Often, three chain-like strands appear to assemble into parallel, ribbon-like structures where rings of neighboring strands are in lateral contact. Several ribbons form a belt which wraps helically around the cell. The cells appear to be completely covered by these belts. The strand structures are located in the periplasmic space and are associated with the outer membrane. A significant amount of strand-like structures was released only after lysozyme treatment, which suggests that the strands are also associated with the thin peptidoglycan layer. It is hypothesized that the connection between a ring element and the elongated element may be flexible and may be the site of force generation during gliding (Fig. 5) (38, 75).

Type IV pili. In early motility studies on *M. xanthus*, pili were recognized to be required for S motility (61). Pili, which are comprised of proteinaceous filaments 10 nm in diameter and 3 to 10 μ m long, are localized predominantly at one cell pole (61, 78) (Fig. 6). Recent studies revealed that these pili belong to the class of type IV pili which are also required for twitching motility. Twitching has been observed in many gram-negative microorganisms, including *Eikenella corrodens*, *Moxarella osloensis*, *Neisseria gonorrhoeae* (52, 73), enteropathogenic *Escherichia coli* (114), *Pseudomonas aeruginosa* (28, 132), and many other pseudomonads (16, 17, 52, 53, 54). Type IV pili are also referred to as type 4 fimbriae. In addition to their role as potential motility organelles, the type IV pili are essential components of several important cellular functions including adhesion to surfaces and phage binding. Molecular details of assembly and function of type IV pili in *M. xanthus* are discussed below in the context of S motility.

Motility Mutants of *M. xanthus*

In the following section, genes and the corresponding mutant phenotypes that are involved in *M. xanthus* motility are discussed. Emphasis is placed on the function of the A- and S-system genes and on how the function of the *fz* and *mgl* genes relate to single-cell gliding and movement of cell swarms.

The A-motility system controls single-cell gliding. Single cells are visible at the edge of A-motile colonies (Fig. 2C). Videomicroscopy analysis of A-motile cells shows that individ-



ual cells glide with wild-type speed when well isolated from other cells (Fig. 2A and C), suggesting that the A-motility system includes all components needed for the machinery and the control of gliding of single, isolated cells. However, compared to the wild type, fewer cells appear to organize into small groups at the perimeter (57) (Fig. 2C). The rate of swarm expansion of A^+S^- cells depends on the cell density to a similar extent to that of A^+S^+ cells (half-saturation cell density about 10^8 cells/ml). The maximal swarming rate is only 0.65 $\mu\text{m}/\text{min}$ on 1.5% agar (62). A^+S^- cells are capable of performing elasticotaxis (37). In fact, the elasticotaxis response in these strains is more pronounced than in the wild-type strain DK1622. The swarming of growing A^+S^- colonies is strongly reduced on a low-percentage (0.3 to 0.5%) agar surface, and the swarming rate increases with increasing agar concentration (107).

By definition, genes belong to the A-motility system only if they result in a nonswarming double-mutant colony when they are mutated and introduced into an S-motility mutant (57). Colonies of cells with mutations in the A-motility system (A^-S^+) have flares with a smooth edge where no isolated, individual cells are visible (Fig. 2B). Table 1 summarizes the genes of the A motility system as well as the genes that affect the cellular movement pattern of individual isolated cells. More than 37 different loci of the A-motility system have been identified and appear to map to at least seven clusters on the 9.4-Mbp *M. xanthus* chromosome (26, 56, 63, 76) (Fig. 7). Considering the loci identified by the independent mutant hunts, it appears that the A-motility system has not been saturated by mutagenesis. While mutations in the A-motility system result in obvious defects in vegetative swarming, with some exceptions they do not affect developmental aggregation (56, 57, 77).

All A-motility mutants can be divided into two subclasses, the *agl* and the *cgl* mutants (55, 56) (Table 1, Fig. 8). Currently, 32 *agl* genes and five *cgl* loci (*cglB*, *cglC*, *cglD*, *cglE*, and *cglF*) have been identified (56, 57, 76). If the swarming defect of an A-motility mutant can be complemented by extracellular rescue, i.e., upon mixing mutant cells with wild-type cells or cells of another motility class, the gene is called a *cgl* gene (for contact or conditional gliding). Rescue of A motility is detected in these mutants when single cells and flares of cells emerge from an area where donor cells and recipient *cgl* mutants are mixed (55) (Fig. 8). A-motility mutants that are not rescued by this extracellular complementation are termed *agl* (for adventurous gliding) mutants. Stimulation of A motility in *cgl* mutants requires cell-cell contact between donor and recipient cells on agar. Addition of cell extract or culture supernatant does not rescue single-cell gliding of *cgl* mutants. However, cells that were killed by brief treatment with formaldehyde do stimulate A-motility movements in *cgl* mutants (with the exception of *cglB* and *cglF*) (55). Interestingly, stimulation is most effective if S motility is retained in the recipient strain.

Studies of Tn5 insertion mutants suggested that some A-motility mutants are defective in biosynthesis of the O antigen of

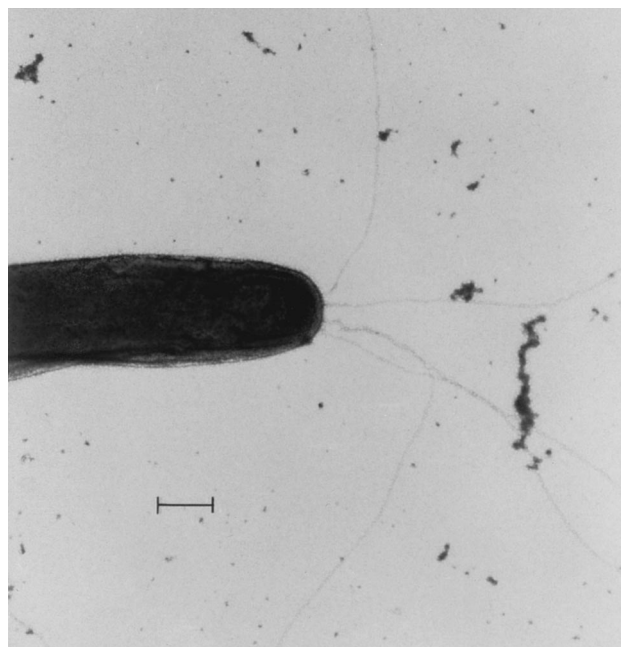


FIG. 6. Polar pili on an *M. xanthus* cell. Picture kindly provided by Dale Kaiser. Bar, 0.5 μm . Reprinted from reference 61 with permission.

lipopolysaccharides (36). Recent findings, however, provide evidence that the motility defects of those *lps* mutants are due to defects in S motility (15). Tn*phoA* mutagenesis resulted in the identification of three mutants that exhibit defects in A motility and that express alkaline phosphatase activity (63). Linkage analysis mapped two of these mutations to the *cglB* and *cglC* loci, respectively, suggesting that these proteins are components of the cell envelope and that they function outside of the cytoplasm.

To date, a detailed molecular analysis of an A-motility gene has been conducted only on *cglB* (101). Videomicroscopy studies of cells with mutations in *cglB* have also been performed (101, 118). Gliding movement of individual *cglB* cells is abolished when the cells are more than 0.5 μm apart from each other (101) (Fig. 2C). When they are in close proximity, extensive cell movement is apparent which is presumably due to S motility (see below), suggesting that A motility controls the gliding of isolated individual cells. The *cglB* gene encodes a 412-amino-acid putative outer membrane protein which contains a typical N-terminal signal peptidase II leader sequence and cleavage site. These findings suggest that the mature protein is localized to the outer membrane, an observation consistent with the Tn*phoA* studies (63). The mature CglB protein is predicted to contain 16 cysteine (excluding the N-terminal) residues, which is an unusually large number for an outer membrane protein. Comparison of the predicted amino acid sequence with sequences in public protein databases suggests

FIG. 5. Chain-like structures proposed to be involved in gliding motility. The images are from *Myxococcus fulvus*, and similar structures were observed in *M. xanthus*. (A) Isolated aggregates of chain-like strands showing different orientations of periodic structural elements. Arrowheads indicate rings. Bar, 50 nm. (B) Regular spacing and positioning of rings normal to the longitudinal axis of the strands (large arrowheads). Three strands form a morphological unit, the ribbon (solid triangles). Long arrows indicate proposed contracted units resulting in a herringbone pattern. Bar, 50 nm. (C) Three-dimensional model of the architecture of strands localized in the periplasmic space and anchored to the peptidoglycan layer and outer membrane. Picture courtesy of Freese et al. Three strands are presented. Conformation of ring elements which are located normal to the outer membrane is shown. The model is not drawn to scale. RE, ring element, framed; EE elongated element; CM, cytoplasmic membrane; OM, outer membrane; cema, central mass; pm peripheral mass. For a description, see the text. Panels A and B reprinted from reference 75 with permission. Panel C reprinted from reference 38 with permission.

TABLE 1. Genes affecting A motility and/or gliding of individual, isolated cells^a

Gene, locus or gene cluster	Molecular properties	Function (putative or proposed) in motility	Assignment ^b	Reference(s)
<i>agl</i> genes				
<i>aglA-R</i>	Unknown	Unknown	g	56
A1 cluster (Ω 1215, Ω 1218, Ω 1221, Ω 1296, Ω 1635)	Unknown	Unknown	g	76
A2 cluster (Ω 1272, Ω 1616)	Unknown	Unknown	g	76
A3 cluster (Ω 1293, Ω 1305)	Unknown	Unknown	g	76
A4 cluster (Ω 1284, Ω 1323, Ω 1632, Ω 1626)	Unknown	Unknown	g	76
A5 cluster (Ω 1302, Ω 1317)	Unknown	Unknown	g	76
<i>mglA</i>	p ^{ras} -like GTPase	Control of single-cell reversals and gliding speed	g	48, 77, 118
<i>mglB</i>	Protein with Ca ²⁺ binding motif	Control of single-cell reversals and gliding speed	c	49, 118
<i>cgl</i> genes				
<i>cglB</i>	Lipoprotein with high cysteine content	Unknown	g	63, 76, 101
<i>cglC</i>	Unknown	Unknown	g	76
<i>cglD</i>	Unknown	Unknown	g	76
<i>cglE</i>	Unknown	Unknown	g	76
<i>cglF</i>	Unknown	Unknown	g	76
Ω 302	Unknown	Unknown	g	63
Ω 334	Unknown	Unknown	g	63
Other genes				
<i>frzA</i>	CheW homolog	Control of single-cell reversals, coupling of FrzCD and FrzE	c	12
<i>frzB</i>	No homology to Che protein	Control of single-cell reversals	c	12
<i>frzCD</i>	MCP homolog	Control of single-cell reversals	c	12
<i>frzE</i>	Response regulator containing a CheA-like histidine autokinase and a CheY-like receiver domain	Control of single-cell reversals	c	12
<i>frzF</i>	CheR homolog	Control of single-cell reversals	c	12
<i>frzZ</i>	Protein with two CheY-like domains	Control of single-cell reversals	c	123

^a Movements of isolated single cells are movements when cells are >0.5 μ m apart from each other.

^b Indicates the criterion used to assign a gene to the A-motility system or to gliding as individual, isolated cells. g, in a genetic cross with an S⁻ mutant the resulting colony was nonswarming; c, the single-cell motility behavior was different from wild type.

that CglB is a unique protein (101). Studies with a *cglB* allele which encodes a CglB protein with 6 histidine residues tagged at the C terminus (CglB-His) showed that this protein is active and promotes single-cell gliding at wild-type velocity (101). However, cells that carry only the CglB-His protein do not stimulate Δ *cglB* mutants to glide, presumably due to a reduced level of CglB-His protein. Because of the *cglB* phenotype, at least two distinct functions of CglB are possible: (i) CglB may be involved in the gliding motor of the A-system as part of the force-generating complex or in the process of force transmission to the surface, or (ii) CglB may function as a signaling molecule and may stimulate single cells to move, e.g., by suppressing reversals. The above-discussed observation on the *cglB-His* allele may suggest that a regulatory role of CglB is less likely than a mechanistic function and that the observed stimulation may reflect localization of CglB to the outer membrane (101).

The S-motility system controls gliding of cells in swarms. S-motile colonies show a clearly defined, undulating edge which is indicative of movement of cells within the colony (Fig. 2B). The cell density dependence of the swarming rate is decreased in these mutants compared to the wild type. The maximal swarming rate of three A⁻S⁺ strains tested is approxi-

mately 0.45 μ m/min, with a half-saturation cell density of 7×10^8 cells per ml (62). Cells that are motile by S motility only are unable to respond to physical stress forces in the substratum (37). Accordingly, the absence of S motility causes a dramatic reduction in swarming of growing A⁺S⁻ colonies on a 0.3% agar surface, and the swarming rate increases with increasing agar concentration (107). Most of the S-motility mutants are also defective in fruiting-body formation (57, 77).

In contrast to A-motile colonies, no single cells are visible at the perimeter of S-motile colonies. To develop an understanding of cellular motility that is due to S motility exclusively, translocation of single cells of a *cglB::TnphoA* strain (A⁻S⁺) was studied (118). Individual cells were found to move only when they were no more than 2 μ m apart (56, 118) (Fig. 2B). The movements, most of which occur in the direction of the long axis of the cell, are jerky but occur at similar high speeds to those observed in wild-type cells (118) (Fig. 2B). Additionally, these A⁻S⁺ cells reverse the direction of movement at a frequency of approximately 2.7 reversals per min, which is more than 10-fold higher than in wild-type cells (0.17 per min). In general, the high-reversal mode of *cglB* mutants is observed mostly at the edge of a group of cells (118). However, these A⁻S⁺ cells are not locked in a high-reversal mode, because

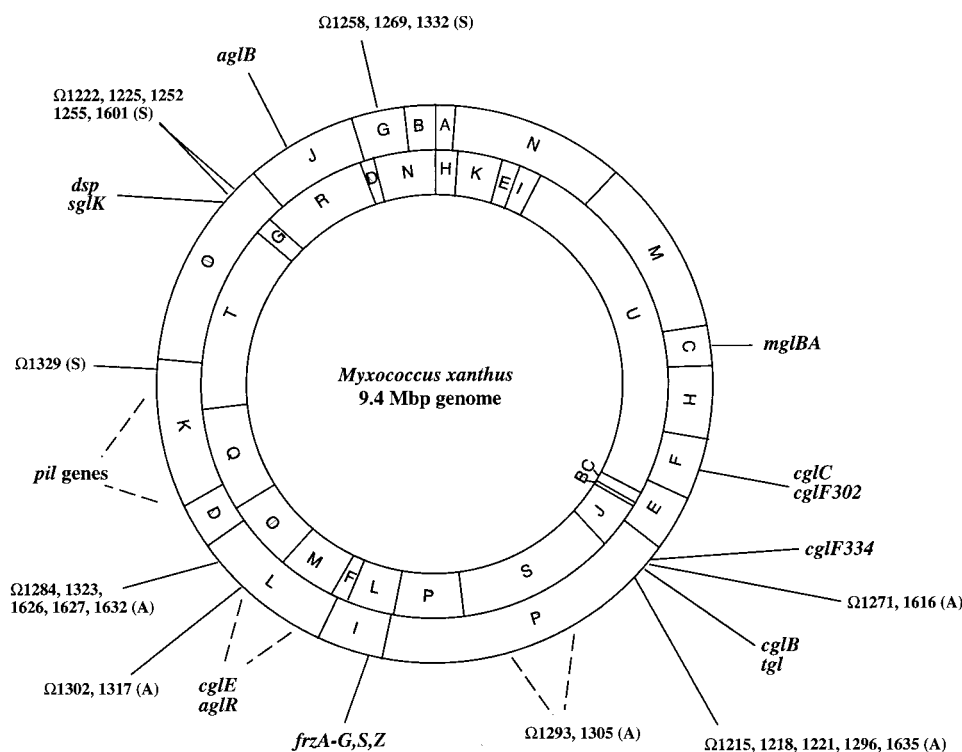


FIG. 7. Localization of motility genes on the *M. xanthus* genome. *AseI* (outer circle) and *SpeI* (inner circle) restriction maps of the DK1622 chromosome are shown. Modified from references 26 and 76 with permission.

cells are able to switch quickly into a low-reversal, high-velocity mode when they are located inside a group of cells. This motility behavior may represent the type IV pilus-dependent gliding in *M. xanthus* and may be related to twitching. As indicated above, pili were recognized to be required for S motility (61).

(i) **pil genes.** Analogous to defining A motility, genes belong to the S system if they result in a nonswarming double-mutant colony when they are mutated in an A^-S^+ mutant (57). Numerous S-motility genes have been identified in mutant screens (Table 2). In the original genetic analysis by Hogkin and Kaiser, two major regions of S-motility genes were identified, the *sglI* and *sglII* regions (57). In recent research, it became clear that most of the *sgl* genes of the *sglI* region showed significant similarity to genes involved in pilin expression and processing and in export, assembly, and function of type IV pili in other bacteria. Therefore, these genes were concluded to be *pil* genes

(126, 137–140, 141) (Fig. 9). Twitching motility is a type IV pilus-based mode of surface translocation and has been observed in many gram-negative microorganisms (16, 17, 28, 52, 53, 54, 132). Our current understanding of type IV pilus structure and biogenesis rests mostly on studies conducted with *P. aeruginosa* and *N. gonorrhoeae* (for recent reviews, see references 3, 30, and 39). Genes involved in type IV pilus export and assembly have multiple homologs to components of DNA uptake and protein secretion systems. These systems have in common that they catalyze a vectorial transport of larger polymers (polypeptides, DNA) across the outer and inner membranes of gram-negative bacteria. These transport systems can function either for import (DNA) or for export (pili, proteins). The strong similarity between the gene products in these systems suggests that these different systems may operate by a common mechanism. In the following discussion, only the

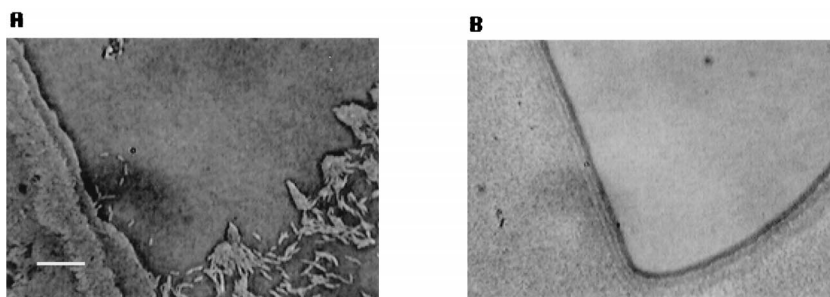


FIG. 8. Stimulation of motility of the *agl* and *cgl* A-motility mutants. Drops (on the left of each image) of a liquid culture of A-motility mutants (A^-S^+) (recipient cells) were spotted on CTT agar plates and allowed to dry, and another drop of DK6204 (donor cells), a nonswarming $\Delta mglBA$ mutant, was added to intersect with the former spot. (A) *cgl* recipient strain (A^-S^+). After a few hours, single cells of DK1219 are visibly gliding as individual cells. (B) *agl* recipient strain (A^-S^+). No stimulation of single-cell movement is observed. Bar, 20 μ m.

TABLE 2. Genes affecting S motility and/or gliding of cells in groups^a

Gene, locus, or gene cluster	Molecular properties	Function (putative or proposed) in motility	Assignment ^b	Reference(s)
<i>sgl</i> genes				
<i>pilA</i>	PilA protein	Major pilin subunit	g	57, 140
<i>pilG</i>	No homolog	Involved in protein secretion	g	57
<i>pilH</i>	ABC transporter	Involved in protein secretion	g	57, 141
<i>pilI</i>	No homolog	Involved in protein secretion	g	57
<i>pilD</i>	Leader peptidase/N-methylase	Processing of pre-PilA protein	g	57
<i>pilQ</i>	Secretin	Synthesis, export, assembly, and function of type IV pili	g	125
<i>pilB</i>	Membrane-associated protein with nucleotide binding site	Involved in pilus assembly	g	57
<i>pilC</i>	Inner membrane protein	Involved in pilus assembly	g	57
<i>pilT</i>	Membrane-associated protein with nucleotide binding site	Involved in pilus retraction?	g	57
<i>pilS</i>	Sensor kinase	Regulation of <i>pilA</i> transcription	g	57, 140
<i>pilR</i>	Transcriptional regulator	Regulation of <i>pilA</i> transcription	g	57, 140
S1 cluster (Ω 1222, Ω 1225, Ω 1601, Ω 1252, Ω 1255)	Unknown	Unknown	g	76
<i>sglK</i>	DnaK chaperone homolog	Protein and polysaccharide secretion	g	76, 129
S2 cluster (Ω 1258, Ω 1269, Ω 1332)	Unknown	Unknown	g	76
S3 cluster (Ω 1329)	Unknown	Unknown	g	76
<i>dsp</i>	Unknown	Required for fibril production	g	6, 7, 88a
<i>mgIA</i>	p ^{ras} -like GTPase	Unknown	g	48, 77
<i>mgIB</i>	Protein with Ca ²⁺ binding motif	Unknown	49	
<i>tgl</i> gene				
<i>tgl</i>	Outer membrane lipoprotein with six tandem tetratricopeptide repeats	Involved in pilus assembly?	g	57, 102
Other genes				
<i>frzA</i>	CheW homolog	Control of S motility, coupling FrzCD and FrzE	s	12
<i>frzB</i>	No homology to Che protein	Control of S motility	s	12
<i>frzCD</i>	MCP homolog	Control of S motility	s	12
<i>frzE</i>	Response regulator containing a CheA-like histidine autokinase and a CheY-like receiver domain	Control of S motility	s	12
<i>frzF</i>	CheR homolog	Control of S motility	s	12
<i>frzZ</i>	Protein with two CheY-like domains	Control of S motility	s	123
<i>frzS</i>	Protein contains a receiver domain	Control of S motility	g	127a
<i>difA</i>	MCP homolog	Control of S-motility	g	142
<i>difC</i>	CheW homolog	Control of S motility		142
<i>difD</i>	CheY homolog	Control of S motility		142
<i>difE</i>	CheA homolog	Control of S motility	g	142
<i>wzm wzt wbgA</i>	ABC transporter	Export of O antigen	g	15
<i>lps-1, lps-2, lps-4, lps-5</i>	Unknown	O-antigen biosynthesis	g	15

^a Movement of cells in groups are movements when cells are <2 μ m apart from each other. Note that if a strain contains functional A motility, some aspect of the movement observed in close proximity may also be due to some aspect of A motility.

^b Indicates the criterion used to assign a gene to the S-motility system or to gliding in groups. g, in a genetic cross with an A⁻ mutant, the resulting colony was nonswarming; s, swarming or other behavior was similar to that of S⁻ mutants.

model for type IV pilus formation and function is discussed, without elaborating the experimental evidence in support of that model (see volume 192 of *Gene* [1997] for numerous specific reviews).

In *P. aeruginosa*, the *pilA* gene encodes the prepilin protein, which, upon cleavage of the 6-amino-acid leader sequence and subsequent N-methylation by the membrane-bound PilD protein, forms the major structural subunit of the pilus filament. For pilin export and assembly, a large multimeric protein complex is thought to reach from the inner to the outer membrane.

PilC is a polytopic inner membrane protein (68, 90), and PilQ is an outer membrane protein which forms an oligomeric complex. This complex acts as a gated channel to facilitate the exit of the PilA subunits. A pilus grows by assembling pilin subunits at its base at the export apparatus. Export of pilin requires the activity of PilB, a protein containing a putative nucleotide binding site, which is associated with the inner face of the cytoplasmic membrane. Mutants with mutations in *pilD* are unable to assemble pili even though *pilA* is expressed. PilT and PilU are two PilB homologs. Of particular interest for type IV

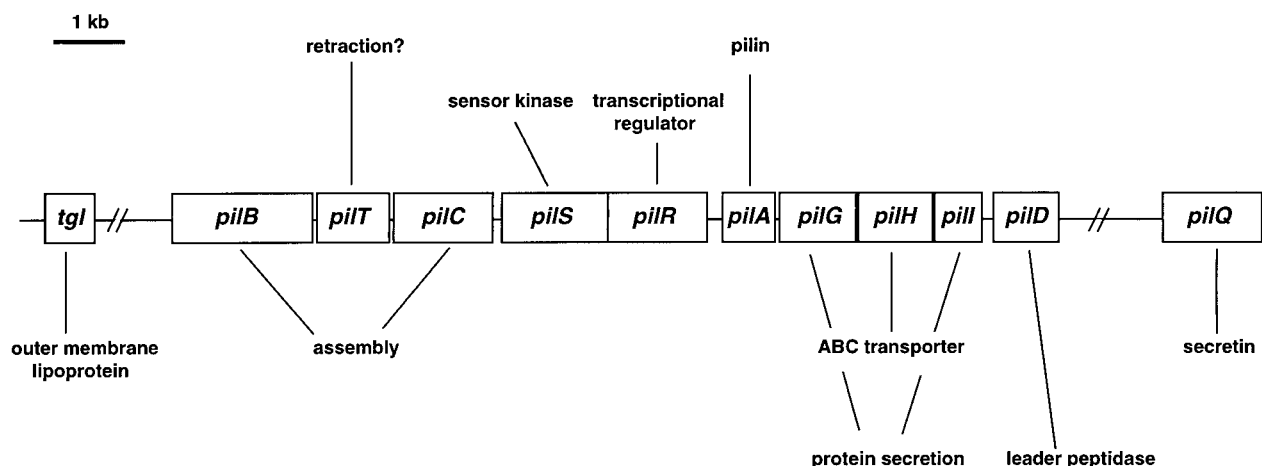


FIG. 9. Organization of *M. xanthus* *pil* genes. Compiled from references 102, 125, and 139 to 141. For details, see the text.

pilus function in twitching motility is *pilT*. The PilT protein is predicted to be a member of a family of nucleotide-binding proteins (132, 139). PilB is required for pilus extension, whereas PilT may catalyze pilus retraction. In *P. aeruginosa*, a set of *pil* genes (*pilGHJK* genes) that show strong homology to the enteric chemotaxis genes and to the *frz* genes of *M. xanthus* were identified (28–30, 144). Mutations in these *P. aeruginosa* genes abolish pilus formation or impair pilus function in twitching (29).

Table 2 and Figure 9 summarize the known *M. xanthus* *pil* genes and the proposed functions of the gene products. The pilin protein, the major constituent of the pilus filament, is encoded by the *pilA* gene. Expression of *pilA* is under control of a σ^{54} promoter, which is regulated by the two-component regulatory system *pilS* and *pilR* (140). Expression of *pilA* requires the response regulator *pilR* as a transcriptional activator but is negatively regulated by the putative sensor kinase *pilS*. Additionally, *pilA* expression is autoregulated (140). Under high-nutrient conditions as well as under developmental conditions, expression of *pilA* is induced but is independent of *pilSR* (140). The homologs of the *M. xanthus* PilB and PilC proteins in *P. aeruginosa* are believed to be involved in pilus assembly (90). PilH is highly similar to an ATP binding cassette (ABC) transporter protein, but PilG and PilI do not reveal homology to known proteins. These proteins are hypothesized to function with PilH (141). In *P. aeruginosa*, *pilD* is a bifunctional leader peptidase and *N*-methylase. *M. xanthus* *pilT* mutants are pilated (139). *P. aeruginosa* (133) and *E. coli* (114) *pilT* mutants are hyperpilated, and twitching motility in these organisms is abolished. Also, *M. xanthus* *dsp* mutants (see below) carry pili but are defective in S motility. Similar to *P. aeruginosa* and *N. gonorrhoeae*, *M. xanthus* contains a *pilQ* gene that is essential for pilus biogenesis (125). The PilQ protein belongs to the secretin superfamily of proteins, which multimerize in the outer membrane to form a channel for uptake of macromolecules (11, 69, 125). Before the molecular similarity to *pilQ* was known, the gene was referred to as *sglA* in *M. xanthus* (125). *pilQ* mutants are frequently isolated as dispersed growing mutants which still form fruiting bodies (e.g., DK101 and DZ1 [125]).

The molecular basis of how type IV pili generate displacement is unknown. The cellular movement patterns observed in the A^-S^+ mutant (*cglB* [see above and reference 118] [Fig. 2]) may reveal the type IV pilus-dependent motility in *M. xanthus*. For nongliding microorganisms, a hypothesis of controlled pi-

lus retraction and elongation was proposed earlier as a mechanism of pilus function which may result in twitching movements (16–18) (Fig. 10). According to that model, a pilus which is attached by its tip to another cell or to a surface could depolymerize and polymerize at the membrane export apparatus, which would result in shortening and extending of the filament and thereby in displacement of the cell (Fig. 10). A depolymerization could be caused by nucleoside triphosphate hydrolysis, e.g., catalyzed by PilT, which could release the energy for pilus retraction. Depolymerization of polar pili would generate movement in the direction of the long axis of the cell. A pilus receptor that could serve as an attachment point specifically for pili from neighboring cells has not been identified, although the fibrils (see below) are certainly good candidates for such function. In gliding microorganisms such as *M. xanthus*, pili of neighboring cells may also attach to surface attachment sites of the A-system gliding apparatus. When these attachment sites undergo gliding-dependent displacements parallel to the cell axis, they can “pull” the pilus and, thus, the neighboring cell. It also seems plausible that in *M. xanthus*, a combination of pilus retraction-extension and pilus displacement along gliding tracks may result in S motility (Fig. 10C). An argument in favor of the latter model is that the A- and S-motility systems do not operate independently. This is indicated by the cell density dependence of the swarm expansion rates in wild-type and in A- and S-system mutants. The rate of expansion of wild-type swarms is higher than the sum of the rates of A^-S^+ and A^+S^- swarms (62). These observations suggest a synergistic effect of the two motility systems.

(ii) ***tgl* gene.** In one S-motility mutant, *tgl* (for transient gliding), S motility and type IV pilus assembly can be stimulated by aligning *tgl* cells with cells of a *tgl*⁺ strain (57, 61, 102, 103, 124, 126). Because of the stimulation phenotype, *tgl* is, in a sense, the counterpart in S motility to the *cgl* genes in A motility. Similar to CglB, Tgl appears to be a lipoprotein which localizes to the outer membrane (102, 103). Tgl contains six tandem tetratricopeptide repeats, a motif which is known to be involved in protein-protein interactions. The observed stimulation by Tgl is believed to be due to Tgl acting as a pilus assembly factor rather than as a cell-cell signal (124).

(iii) **Other S-motility genes.** Next to the *pil* genes and *tgl*, there is a third group of S-motility genes that affects cell surface structures in *M. xanthus*: the genes of the *dsp* locus and the linked *sglK* locus. Both genes are also required for formation of extracellular fibrils (7, 108, 109, 111, 129). Mutants defective in

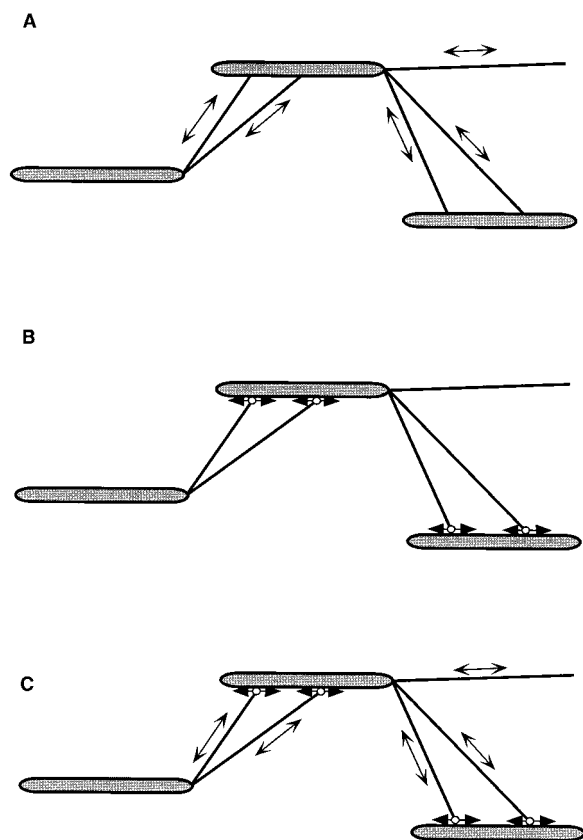


FIG. 10. Models for generation of cell movement by type IV pili in *M. xanthus*. To illustrate the model of pilus-dependent S motility, individual cells are not drawn to be in contact with other cells. It should be noted that cell-cell contact is required for S motility. (A) A depolymerization-polymerization (\leftrightarrow) shortens a pilus, thus generating displacement mostly in the direction of the long axis of the cell. (B) Pili attach to neighboring cells at "adhesion sites" ($\bullet \rightarrow$), e.g., which are part of the gliding motor of A motility and are involved in A-motility-dependent gliding. Linked to the moving adhesion sites by a pilus, a neighboring cell is "dragged" along, thus performing a translocation in the direction of the long axis of the cell. (C) A combination of pilus retraction-extension and adhesion site-dependent displacement (A plus B).

dsp were isolated as S^- mutants and grow as dispersed cultures in liquid medium (88a). When crossed with an A^- mutant, A^-dsp double-mutant colonies show some reduced swarming after prolonged incubation. *dsp* mutants form pili but carry aberrant fibrils and are defective in cell cohesion and development (6, 7). Fibrils are extracellular, irregular branched structures of variable width and length (5, 7) and are required for cell-cell cohesion (5, 6). They are composed of polysaccharides and contain a class of integral fibril protein, IFP-1, which is defined as being released from fibril material only after treatment with sodium dodecyl sulfate and β -mercaptoethanol (8, 9, 129). It has been suggested that the different sizes of IFP-1 proteins result from multimer formation of a single small-molecular-size subunit whose amino acid composition and N-terminal sequence were determined (9). Fibrils are found mostly on cells in groups where they establish cell-cell and cell-substratum contacts (7). A link between exopolysaccharides (fibrils) and type IV pilus-dependent S motility may exist, similar to the link between alginate production and twitching motility in *P. aeruginosa* (131). AlgR and FimS, which are a regulator and a sensor, respectively, are required for alginate production and for twitching motility. This sensor-regulator

couple does not appear to regulate PilA production in *P. aeruginosa* (131), raising the possibility that the produced exopolysaccharides are mechanistically required for twitching movements. Accordingly, fibrils may have an analog function in S-motility gliding of *M. xanthus*.

The developmental defect of *dsp* mutants can be complemented by extracellular addition of isolated fibrils (23). Furthermore, *dsp* mutants are unable to bind Congo red, a dye that binds to extracellular polysaccharides in wild-type *M. xanthus* cells (6). Wild-type cells behave phenotypically as *dsp* mutants upon incubation with Congo red, suggesting that fibrils are required for cell cohesion (5, 6). However, fibrils per se do not seem to be required for S motility and development, because *dsp* second-site suppressor mutants that carry no fibrils exhibit motility and development (24). Also, some recently isolated *cgs* mutants that lack fibrils and are defective in agglutination and developmental aggregation were shown to be proficient in swarming on low-percentage agar (94). Therefore, *dsp* may have several functions including one in fibril production and one in S-motility control. Disruption of the *stk* gene, which presumably is a negative regulator of fibril synthesis, causes overexpression of fibrils as well as increased cell cohesion and dye binding in wild-type cells but not in *dsp* mutants (27). Recently, it was shown that mutants with mutations in the S-motility gene *sglK* are unable to produce fibrils (129). The *sglK* gene product is predicted to resemble a DnaK chaperone homolog (129). It is cotranscribed with another gene that is predicted to encode another chaperone homolog, GrpE. Both chaperones are believed to be involved in protein and polysaccharide secretion (129).

The *dif* genes were recently isolated in a screen for mutants defective in fruiting-body formation (142). Molecular analyses of the *dif* locus revealed four open reading frames, called *difA*, *difC*, *difD*, and *difE*, whose products show significant identity to the bacterial chemotaxis proteins methyl-accepting chemotaxis protein (MCP), CheW, CheY, and CheA, respectively. Interestingly, DifA, a tentative homolog of MCP, shows the strongest identity to the *Bacillus subtilis* TlpB. Mutations in *tlpB* cause *B. subtilis* cells to stick together. Based on the genetic double-mutant test, the *difA* and *difE* genes belong to the S-motility system (142). Very recently, another gene that is believed to be involved in a signal transduction pathway, *frzS*, was shown by the genetic double-mutant test to belong to the S-motility system (127a) (see below). It is tempting to speculate that the *dif* genes, and some *frz* genes, represent a signal transduction pathway involved in the control of S motility that affects the activity of type IV pili (e.g., by controlling retraction, extension, or attachment of the pili) or their expression.

Some O antigens of lipopolysaccharide were recently shown to be required for S motility (15). A null mutant with mutations of the *wzm*, *wzt*, and *wbgA* genes, which map to the *sasA* locus, behaved as an S^- mutant (15). These mutants were previously isolated as mutants that suppress a developmental defect of *asgA* mutants (64).

As indicated above, no direct observation of pilus-mediated cell movement has been reported. However, with many S-motility genes available (Table 2) and in conjunction with high-resolution videomicroscopy, specific models of pilus function can now be tested, and it should be possible in the near future to uncover the molecular mechanism(s) of type IV pilus-mediated movements in twitching and in S-motility gliding.

A^-S^- double mutants. The nonswarming phenotype of A^-S^- double-mutant colonies has served as the conceptual basis for defining the two gliding systems in *M. xanthus* (56, 57). Motility mutants identified by the double-mutant test will most

likely include those defective in structure, assembly, and function of the gliding motor elements (e.g., *pil* genes). Mutations in genes whose products play a modulating role on the activity of the gliding motors may only partially affect the swarming pattern of the A- or S-motility system when observed in a null mutant background of the other motility system. These mutants may exhibit reduced but not completely abolished movements. For example, mutations in *frzCD*, *frzF*, or *frzE*, when crossed into an A⁻ mutant, show a reduced S-motility swarming (37) (Tables 1 and 2; also see below). Also, genes of the *dsp* locus may play a regulatory role in S motility, because S-system swarming is severely reduced in A⁻*dsp* double mutants.

Motion analysis of single *cglB pilR* (A⁻S⁻) cells revealed that the cells are not completely nonmotile, as might have been suggested from the nonswarming colony morphology, but are able to conduct a few single-stroke movements (118). A stroke movement consists of a small (~1- to 1.5- μ m) displacement, followed by a pause for at least 20 min. Most cells did not move during the observation period. One possible rationalization of this residual movement is that because of the *pilR* mutation, no functional pili are present, which eliminates any pilus-dependent S motility as a cause of the residual movement (118, 140). The mutation in the A system abolished the gliding of isolated single cells. In the absence of a clear understanding of the A-system gliding apparatus, however, it is not obvious that a null mutation in A motility, such as Δ *cglB*, results in a knockout mutant in the A-system gliding motor. It is conceivable, for example, that some A-system mutants, like the *cgl* mutants, are defective in transmission of force between the cell body and the substratum, e.g., because they lack gliding-specific adhesion sites. Such mutants would behave as A-motility mutants in swarming and single-cell assays but would still have an A-system gliding motor that is proficient in force generation. In the absence of such a specific adhesion site for A motility, other components of the cell envelope may be poor substitutes in force transmission, thus resulting in ineffective displacement. This could be one scenario to explain the observed residual movement in that particular A⁻S⁻ mutant. Many *agl* genes are awaiting molecular characterization. One imminent question is also whether the large collection of *agl* and *cgl* mutants contains a mutant that represents a "true" motor mutant. If such a mutant cannot be isolated, this may suggest either that *M. xanthus* carries multiple copies of these genes or that a complete loss of the complex motility apparatus, caused by a knockout mutation, may destabilize the cell wall and result in a lethal phenotype.

Control of *M. xanthus* motility by the *frz* genes. The *frz* locus was identified by a set of mutants which display a unique developmental defect in aggregation and fruiting-body formation (144). Under starvation conditions, these *frz* mutants form entangled, "frizzy" aggregates. To date, seven *frz* genes have been identified within this locus: *frzA*, *frzB*, *frzCD*, *frzE*, *frzF*, *frzG*, and *frzZ* (13, 83, 123). In addition to the aggregation defect, the *frz* mutants carry a defect in colony swarming on low-percentage agar that somewhat resembles that seen in S-motility mutants (37, 107). Mutations in the *frz* genes also reduce the level of sporulation (105, 123) although this effect is strain dependent. Interestingly, single cells of most *frz* mutants have an altered frequency of reversing their direction of movement; wild-type cells reverse their direction once every 5 to 7 min (0.17 reversal min⁻¹), while most *frz* mutant cells reverse on average once per hour (<0.02 reversal min⁻¹). One notable exception was caused by a Tn5 insertion at the 3' end of the *frzCD* gene (a *frzD* mutant). Single cells bearing this mutation exhibit an increased (1.5 reversals min⁻¹) rather than a decreased reversal frequency (12, 118). Gliding velocities, how-

ever, are unaffected in *frzE* mutants, as shown by high-resolution videomicroscopy studies (12, 118).

The amino acid sequences of the predicted Frz proteins show striking similarities to those of the Che proteins involved in chemotaxis of enteric bacteria (13, 83, 87) (Tables 1 and 2). The enteric *che* signal transduction system is a two-component regulatory system, where the input stimulus is the concentration of an attractant or repellent in the environment and the output is a change in swimming behavior (for a recent review, see reference 14). The basic signal relay consists of two interacting proteins, CheA, a histidine kinase that autophosphorylates a histidine residue at position 48, and CheY, a response regulator protein that receives the activated phosphate from CheA at a conserved aspartate residue (Asp 57) in a CheA-dependent transphosphorylation reaction. The phosphorylated form of CheY then interacts with the FliM protein of the flagellar switch to cause a bias of flagellar rotation toward clockwise, resulting in an increased tumbling frequency. Input of environmental signals (attractant or repellent) into the Che signal transduction cascade is mediated by MCPs. These receptors are transmembrane proteins that interact either directly with attractants or repellents or indirectly with periplasmic binding proteins on their periplasmic side and with CheA at their cytoplasmic interface. The interaction between a chemoattractant and its cognate MCP induces a conformational change in the MCP which results in inhibition of the CheA autokinase activity. CheW is involved in mediating the interaction between the MCPs and CheA. Another protein, CheZ, catalyzes the dephosphorylation of the response regulator, CheY, ensuring that only the most recently sensed change in stimulus concentration is integrated into a motility response. Adaptation, or the control of sensor sensitivity, is regulated by the extent of methylation of specific glutamate residues on the cytoplasmic domain of the MCP proteins. The activities of two enzymes control the state of methylation; the CheR methyltransferase uses S-adenosylmethionine as a methyl group donor to methylate the cytoplasmic domain of a MCP, while the phosphorylated form of CheB, which has methyl-esterase activity, demethylates the protein. In some nonenteric bacteria (e.g., *Rhizobium meliloti* and *Rhodobacter sphaeroides*), Che homologs are involved in chemokinetic rather than chemotactic behavior, and cells respond to an absolute concentration of chemoattractant rather than to a gradient, by swimming at different speeds (4, 115, 116).

In *M. xanthus*, the *frz* genes include homologs of *cheA*, *cheY*, *cheW*, *cheR*, and *cheB*, as well as genes containing combinations of different domains of *che* genes and genes which show no match with *che* genes (Table 2). For example, the *M. xanthus* FrzE protein contains a CheA-like histidine kinase domain and a CheY-like regulator domain, while FrzZ is predicted to contain two CheY domains. The proposed receptor, FrzCD, which is considered to be a MCP homolog, does not contain either a membrane-spanning region or the periplasmic domain of the enteric MCPs and is a cytoplasmic protein (82, 83). Since *frz* genes are defined by the "frizzy" aggregation phenotype under developmental conditions which involves A- and S-motility movements, the control of *M. xanthus* motility by *frz* genes appears to be more complex than the Che cascade, which regulates only one motor in swimming bacteria.

Biochemical studies have demonstrated that the Frz proteins can act as a signal transduction system operating by a phosphorelay mechanism. In vitro experiments with recombinant FrzE and [γ -³²P]ATP demonstrated that FrzE is capable of autophosphorylation, presumably at a histidine residue (87). This finding, in conjunction with the predicted histidine kinase response regulator fusion of the protein, suggests that FrzE

contains both autokinase and transphosphorylation activity (87) and thus is capable of functioning as a signal relay module (87). Since adaptation in the enteric bacteria requires the reversible methylation of the MCPs, the methylation state of FrzCD has been examined under both vegetative and developmental conditions. Such an analysis was possible since the methylated receptors migrate faster than the unmethylated form during electrophoretic separation on sodium dodecyl sulfate-polyacrylamide gels (82, 86, 89). Similar to the situation in enteric bacteria, methylation of FrzCD is dependent on the methyltransferase FrzF (86).

In recent years, research on the function of *frz* genes has been directed to address two fundamental questions: (i) the identity of the signal input into the Frz cascade, and (ii) the cellular apparatus on which the output signal acts. Due to the similarity between the Frz proteins and the enteric Che system, it was initially hypothesized that motility of vegetative and developmental *M. xanthus* cells could be controlled by regulation of the reversal frequency of the cell. Movement with a low reversal frequency was considered a response to an attractant, and movement with a high reversal frequency was considered a response to a repellent (81). Extensive studies have been conducted to identify physiological attractant or repellent molecules which could cause altered, Frz-dependent motility behavior and would affect the methylation state of FrzCD. It was hypothesized that by analogy to enteric MCPs, an increase in the amount of the methylated form of FrzCD might represent an adaptive response to an attractant stimulus and, similarly, an increased level of demethylated FrzCD may indicate adaptation to a repellent (81). Since chemotaxis requires an adaptive response, the ratio of methylated and unmethylated FrzCD was used to test a large number of molecules as potential chemoattractants or repellents (84, 105). Casitone and yeast extract was found to increase the level of methylated FrzCD, whereas some short-chain alcohols, including isoamyl alcohol, were found to decrease the level of methylated FrzCD (84). Isoamyl alcohol, which has not been reported to be an intermediate in *M. xanthus* metabolism, increased the reversal frequency of single wild-type cells when added at a high concentration (ca. 30 mM) (105). This response of vegetative cells required *frzA*, *frzCD*, and *frzE* (105). However, single cells exposed to gradients of potential attractants did not show changes in motility behavior (32, 122). While the observed responses to repellents are consistent with the enteric paradigm, responses to attractant stimuli are more complex and are now believed to include chemokinetic behavior in response to some self-generated stimulus (127). Recently, phosphatidylethanolamines, including those found in *M. xanthus*, were reported to behave as chemoattractants in swarm and single-cell motility assays (66). The motility response is specific to a particular composition of fatty acid and correlates with a decrease in reversal frequency of individual cells. Over a period of 1 h, the suppressed reversal frequency returned to the "prestimulus" level. This observation was interpreted as adaptation, suggesting that cells may indeed respond chemotactically to these compounds. Interestingly, these behaviors were only partially dependent on intact *frz* genes, which suggests the existence of an additional signal transduction cascade required for responses to phosphatidylethanolamines (66).

The *frz* genes are developmentally regulated (130), and the Frz proteins are activated during development, as indicated by increased FrzCD methylation (84). One developmentally regulated molecule has been identified as a positive input signal to the *frz* system: the extracellular C-factor signaling protein required for fruiting-body formation and sporulation. During an analysis of the C-factor signaling pathway, *Tn5lac* mutants

which arrested at the aggregation stage were identified (113). One subclass of these transposon insertions mapped to the *frz* locus, while a second subclass mapped to the *fruA* locus (previously the class II gene). These mutants were blocked at a similar stage in aggregation to *csgA* mutants but sporulated at a level higher than that of *csgA* mutants, which do not produce C factor (113). It was suggested that C factor is a component of two separate pathways, one that regulates developmental aggregation and one that regulates sporulation. The ratio of methylated to unmethylated FrzCD protein was used to examine whether C factor can function as an input signal to the *frz* cascade. Addition of purified C factor to developing cells of a *csgA* strain resulted in an increase in the methylated form of FrzCD as detected by Western blot analysis (112). This methylation was dependent on the C-factor concentration and did require FrzF, the putative methyltransferase in *M. xanthus*. Other developmental mutants that are defective in production of other development-essential extracellular signals were found to be defective in FrzCD methylation as well (40). These observations demonstrate that the *frz* signaling cascade is activated under developmental conditions of coordinated cell movements during aggregation and fruiting-body maturation in response to cell-cell signals.

While several recent studies have identified compounds that could provide input to the Frz cascade, some advances relating to the output of the system have occurred. The recently discovered *dif* genes, which also show strong similarity to bacterial chemotaxis proteins, seem to affect only S motility, because the reversal frequency of *difA* and *difE* mutant cells is unaltered from that of the wild type (142). This is in contrast to *frz* mutant cells. Because of the complexity of the Frz components and the motility responses, it seems possible that the Frz output interacts with both the A- and S-motility systems. An output of Frz into the A-motility system is indicated by an altered reversal frequency of isolated *frz* cells. No mutations that suppress the low-reversal phenotype of *frzE* mutant cells have been reported. Many observations also hint at S motility as an output of Frz. (i) The swarming motility of vegetative *M. xanthus* depends on the agar support; low-percentage agar (0.3%) is almost exclusively conducive to S motility of swarms (37, 57, 62, 107). Vegetative swarming in response to Casitone and yeast extract, and also to isoamyl alcohol, was most dramatic on 0.3% agar (105). This response depends on the *frz* genes (*frzA*, *frzB*, *frzCD*, *frzE*, and *frzF*). (ii) Suppression of the swarming defect of some *frz* mutants (*frzF*, *frzCD*) is specific to the *sglA1* (*pilQ*) allele (65). Transposon insertions in *frzF* and *frzCD* render starving *M. xanthus* cells unable to form aggregates at low cell density, and sporulation is reduced to only 1% of the wild-type level in a *sglA1*⁺ background. However, in a *sglA1* (*pilQ*) mutant background, the low-cell-density aggregation defect is suppressed and double-mutant colonies form frizzy aggregates. Notably, *frz* mutants were identified in a *sglA1* mutant background (144). At high cell density, the partial sporulation defect of the *frz* mutants is suppressed by *sglA1* (*pilQ*). This suppression may not be due to S motility per se as indicated by the specificity; only a *sglA1* (*pilQ*) allele but not *pilC* (*sglG*) promotes suppression. (iii) Similar to S⁻ mutants, *frz* mutants are not defective in elasticotaxis, a response that appears to be specific to the A-motility system (37). (iv) A *frzD* mutation can partially suppress the swarming defect of an *mglBA* mutant (118) (see below). (v) In *P. aeruginosa*, a set of genes required for pilus biogenesis and twitching motility that shows strong homology to *che* genes, specifically the *frz* genes of *M. xanthus*, was found (29). Since mutations in some of these genes block pilus production and a *pilH* mutant exhibits a "frizzy"-like swarming pattern, it was suggested that these

Che-like proteins control twitching motility in *P. aeruginosa* (29). Because functional type IV pili are required for S motility in *M. xanthus*, it is tempting to speculate that one mode of action of the *frz* gene products is to control type IV pilus-dependent movement. The postulated mode of pilus action, i.e., retraction and/or extension, could result in phenotypic reversals (see also Fig. 10). Also recently, it was postulated that in addition to the *frz* genes, other signaling cascades that are necessary for developmental motility behavior may exist (66). (vi) *frzS* was recently identified as a new *frz* gene which, when mutated, results in a "frizzy" phenotype (127a). In contrast to the other *frz* mutants, no effect on the cellular reversal frequency was found. Moreover, *frzS* was shown to belong to the S-motility system as indicated by the genetic double-mutant test (127a). (vii) The *dif* genes, which also show homology to the enteric *che* genes, were recently identified in *M. xanthus* and appear to also affect S motility (105). Considering these observations, it seems likely that Frz affects S motility.

Motility and the *mgl* genes. In addition to isolating A- and S-motility mutants, Hodgkin and Kaiser identified one locus that, with a single mutation, rendered a colony completely nonswarming (57). Ten independent mutations were identified in this locus. Because of the colony-swarming defect, this locus appeared to be essential to both A and S motility and was called *mgl* (for mutual function for gliding). Therefore, it was reasoned that the *mgl* gene(s) might encode components of the gliding motor. In addition to abolishing swarming, *mgl* mutants are defective in fruiting-body formation and sporulation, presumably due to their inability to conduct C-factor signaling during development (70, 120). A molecular analysis of the *mgl* locus revealed that the *mgl* operon contains two genes, *mglA* and *mglB* (120, 121). A mutation in *mglA* causes the severe swarming and developmental defect, whereas *mglB* mutant colonies exhibit only partially reduced swarming, aggregation, and sporulation (49). This reduced swarming correlates with the reduced cellular level of the cytoplasmic MglA protein (49). A stabilizing interaction between MglA and MglB is suggested by the finding that in an *mglB* mutant, the cellular level of MglA is only 15 to 20% of that in wild-type cells but the level of *mglBA* mRNA is unaffected (49). MglA is not essential for growth.

High-resolution motion analysis of single $\Delta mglBA$ cells revealed that despite the nonswarming colony phenotype, individual cells are motile (118). The movement pattern of $\Delta mglBA$ cells, however, is distinctly different from that of the wild type and all other *M. xanthus* motility mutants that were examined. Individual $\Delta mglBA$ cells translocate by abrupt, jerky displacements and can reverse the direction of movement about 2.9 times per min, which is more than 10-fold higher than in wild-type cells. The average translocation speed is reduced to 1.9 $\mu\text{m}/\text{min}$. As a result, cells perform a net movement of less than 1 μm in 9 min. These movement patterns are different from those of wild-type cells; of A^-S^+ cells, which reverse similarly often but also translocate by extended, unidirectional movement at high speed (4.7 $\mu\text{m}/\text{min}$) (118; see above) (Fig. 2B); of A^+S^- cells, which glide with wild-type speed when separated from other cells (Fig. 2C) and exhibit normal reversal frequencies; and of A^-S^- double mutants, which conduct only short, single-stroke displacements and which do not move most of the time (118). Interestingly, the high-reversal phenotype of $\Delta mglBA$ mutant cells as well as the movement activity of the overall population is dependent on the presence of pili (118); in $\Delta mglBA$ *pilR* double-mutant cells, the high-reversal pattern and the jerky movement are reduced (118). Single cells of an *mglB* mutant exhibit an intermediate phenotype; the reversal frequency is 1.8 times min^{-1} and the

average translocation speed is 2.6 $\mu\text{m}/\text{min}$ (118). Such an intermediate phenotype correlates with a reduced level of cellular MglA protein in *mglB* mutants. The above observations suggest that a correct level of MglA is required for *M. xanthus* cells to move with wild-type speed and wild-type reversal frequency. Because the movement pattern of $\Delta mglBA$ cells is dependent on S motility and because $\Delta mglBA$ cells have pili (although at reduced levels), it seems that $\Delta mglBA$ mutant cells behave more like a strong A-system mutant (abolished single-cell movement, high-reversal mode when cells are in close proximity) with an only partially defective S-motility system (no extended runs in one direction at high speed, requirement for pili, and movement distinguishable from that of a A^-S^- double mutants). Therefore, the cellular motility phenotype suggests that *mgl* function affects the A- and S-motility system differently (118).

The predicted amino acid sequence of the 195-amino-acid MglA protein reveals homology to the nucleotide binding site of Sar1 and $p21^{\text{ras}}$, both of which belong to the class of small eukaryotic GTPases (48, 49). These GTPases are regulatory proteins which play crucial roles in signal transduction, cytoskeleton organization, protein trafficking, and organelle functions (80). Small GTPases, such as $p21^{\text{ras}}$, have two protein conformations depending on whether they are in the GTP-bound or the GDP-bound state. Interaction with GTPase-activating proteins and guanine nucleotide release factor proteins are believed to regulate the transition between the conformational states. MglB is predicted to be a 159-amino-acid protein that includes a region resembling a calcium binding site of yeast calmodulin (49). Calcium is required for gliding in *M. xanthus* and in *Stigmatella aurantiaca* based on Ca^{2+} ionophore and inhibitor studies (136). To examine whether MglA may function in *M. xanthus* in a mode similar to that of Sar1, genetic complementation studies of a $\Delta mglBA$ mutant with *Ha-ras* and *SAR1* of *Saccharomyces cerevisiae* were conducted (47). When inserted in the *M. xanthus* genome, *SAR1* complemented the sporulation defect of the parent $\Delta mglBA$ mutant (47). A *SAR1* allele with defective GTPase activity did not complement the sporulation defect, demonstrating that sporulation requires a functional GTPase activity. Neither *Ha-ras* nor *SAR1* complemented the motility defect. Interestingly, a second-site mutation in a gene called *rpm* (for restore partial motility), is necessary to partially suppress the swarming defect of a $\Delta mglBA$ *SAR1* strain. This suppression seems to be allele specific. These findings support the notion that *SAR1* affects sporulation and motility differently and that *SAR1* may interact with another protein to control motility. The $\Delta mglBA$ *SAR1 rpm* strain swarms on 0.3 and 1.5% agar, suggesting that A and S motility, as indicated by enhanced swarming, was restored. Interestingly, the S-motility system swarming defect of *mglBA* colonies can be partially suppressed by a *fzrD* mutation (118).

In summary, MglA appears to be a small GTPase that is crucial for several independent cellular functions, i.e., development, sporulation, and motility, and may affect these cellular functions in different ways. With respect to motility, MglA appears to represent, next to the A- and S-motility systems, a novel element that controls motility. Work at the molecular level is required to uncover the mode of action of this remarkable protein.

Model for Single-Cell Gliding (A Motility) in *M. xanthus*

Considering the above-discussed genetic, molecular, ultrastructural, and behavioral studies of *M. xanthus*, it is tempting to summarize these observations in the following speculative model for A-motility gliding of isolated *M. xanthus* cells (Fig.

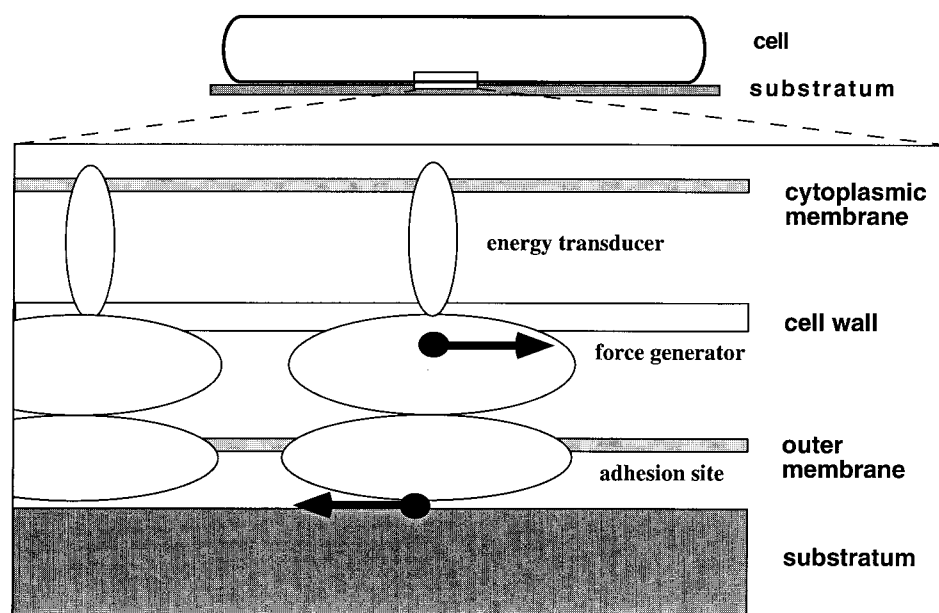


FIG. 11. Speculative model for single-cell gliding (A motility) in *M. xanthus*. The picture is a close-up of the interface of the surface of a gliding cell with the substratum and shows one of the numerous motor units in detail. The cell is moving from left to right. In this model, the force generator (molecular motor) is anchored to the cell wall (rigid peptidoglycan layer), which functions as a skeleton of a bacterial cell. A force of action is generated mainly in the direction of the long axis of the cell and is coupled to an adhesion site in the outer membrane, which interacts with the substratum. Because the coupling of the adhesion site to the surface is tight, the force generator moves to the right relative to the adhesion site, and the relative displacement is indicated by the arrows. The chemical energy that the force generator transforms into mechanical work is delivered by an energy transducer and is derived from the electrochemical ion potential across the cytoplasmic membrane.

11). This model also rests on observations and models, formulated for *Cytophaga* strain U67 and *Flexibacter*, that were conducted by Lapidus and Berg (72), Ridgway and Lewis (100), and other authors (see below) on other gliding bacteria. It should be kept in mind that because of the operational definition of gliding, the molecular mechanism(s) to achieve gliding movement of well-isolated single cells can differ among microorganisms.

Based on observations on the motility behavior of individual cells as well as on bead movement along the cell surface, it is generally believed that multiple motor elements exist along the cell body (see above) (45, 72, 100, 117). Because a gliding cell moves only when the force of action is generated at a rigid cellular structure such as the cytoskeleton or the cell wall, it is expected that the force-generating elements for gliding are connected with the cell wall as well as with the substratum (Fig. 11). This predicts that the motility apparatus catalyzing the conversion of chemical energy into mechanical energy may not be localized inside the cytosol. In general, ATP is not believed to be present in the periplasmic space, and in *Flexibacter*, gliding is most likely to be powered by the proton motive force (98). It is tempting to speculate that in *M. xanthus*, the energy for A-motility gliding is also directly derived from the proton motive force. A model for energy transduction between the cytoplasmic membrane and the periplasmic motor elements can be developed by analogy to the function of the energy transducer TonB. TonB, in a complex with ExbB and ExbD, mediates the active transport of iron siderophores across the outer membrane in *E. coli* (for a recent review, see reference 88). TonB is a cytoplasmic membrane protein that extends through the periplasmic space to contact the iron chelate receptor in the outer membrane. Energy is transduced to the receptor via proton motive force-induced conformational changes of the proteins involved. Accordingly, in A-motility system gliding, the energy of the proton motive force could be

transduced by a TonB-like protein or protein complex to induce a conformational change in the gliding force generator.

It can be speculated that the products of A-motility genes include those that specify the structure of the gliding motor and gliding-specific adhesion sites, as well as those required for assembly of the structure, energy transduction, and regulation of the motor activity. A motility operates best on high-percentage agar surfaces, and A-motile cells respond to stress forces in the substrate matrix. These observations are consistent with the notion that cellular motor elements interact with rigid polymers in the substratum surface, e.g., in the process of force transmission. On a low-percentage agar surface, only few contact points are available, which could explain the reduced swarming by A motility in A^+S^- cells on that surface. CglB could be required for force transmission to the substratum. The residual movement observed in the A^-S^- (*cglB pilR*) mutant could be due to ineffective force transmission by other, less specific molecules. Such function of the CglB protein is consistent with its property of being transferred between cells under certain conditions.

Although presently no experimental evidence exists that the chain-like structures are the motor elements for gliding, they nevertheless fit certain requirements expected for the gliding motor (Fig. 5 and 11). For example, the superstructure is anchored to the peptidoglycan layer and is in contact with the outer membrane. The chain-like strands that assemble in larger periodic ribbon-like and belt-like structures cover the complete cell in a longitudinal fashion. A ring could, in a sense, represent a single motor element. The fundamental step in force generation of this motor element could be a conformational change of the ring structure with respect to the elongated filaments in form of a tilt. Such a tilt would result in a small displacement of the outer perimeter of a ring with respect to the elongated filament. Because the outer perimeter of a ring is postulated to be in contact with the adhesion sites in

the outer membrane, the vectorial force along the long axis of the cell is transduced to the substratum. Alternatively, a tilting of the rings in a way like that described by Freese et al. (38) could lead to a local contraction of the superstructure and thus transduce the force as well. A "relaxation" of that conformational state would be required for the molecular motor to return in its prestroke state. Because each strand contains a large number of ring-like structures, a *M. xanthus* cell carries multiple motor elements along the complete cell body. The presence of multiple motor elements were predicted from studies of U-shaped cells and of cells that are fortuitously attached with only one cell pole. The bead movement observed along the entire cell body may also support this hypothesis. Bead movement in the opposite direction of the cell translocation may indicate that the beads tagged the relaxation to the prestroke state.

Although the above-described thoughts are very hypothetical, some specific hypotheses can be derived and tested in experiments. These questions include the following. Is the superstructure involved in gliding? Is the observed cellular structure the molecular machinery that converts chemical energy into mechanical work? How is force transmitted to the substratum? How is the activity of a motor element regulated? How is gliding speed regulated? Is it due to adjustable activities of individual motor elements or to activation of different quantities of motors that operate in an on-only/off-only mode? Furthermore, how is the gliding movement of isolated single cells coordinated to result in macroscopic A motility, and how is type IV pilus-dependent movement coordinated to result in S motility?

GLIDING MOTILITY IN *FLAVOBACTERIUM JOHNSONIAE* AND *CYTOPHAGA* STRAIN U67

Early studies on gliding motility focused on *Cytophaga* spp., since these cells are among the fastest of gliding bacteria, moving at speeds of up to 2 $\mu\text{m/s}$ on a glass surface. Therefore, these gliders can be easily observed under the microscope. Although many similar gliding properties have been observed between *Cytophaga johnsoniae* (which was recently reclassified as *Flavobacterium johnsoniae* [10]) and *Cytophaga* strain U67, the gliding mechanisms used by these species may be distinct. Based on studies of sensitivity to phage infection, *Cytophaga* strain U67 may be a close relative of *F. johnsoniae* (97).

Using video microscopy, Lapidus and Berg (72) conducted thorough behavioral studies on gliding movements of isolated *Cytophaga* strain U67 cells on the surface of glass slides. Slime trails, which were often postulated to be involved in active gliding in other organisms, were not detected in association with *Cytophaga* strain U67 movement. During gliding in either the forward or reverse direction, cells were observed to suddenly enter into abrupt clockwise or counterclockwise rotations (pivoting) around either cell pole at a rate of approximately 0.5 Hz; occasionally, faster pivoting was observed, sometimes for extended periods. Incomplete pivots, or flip-flops, where one cell pole is lifted and deposited somewhere else in the absence of complete rotations, have also been described. *Cytophaga* strain U67 cells were not observed to flex or to rotate during gliding. The gliding speed in *Cytophaga* strain U67 was demonstrated to be independent of the cell length, an observation which has also subsequently been made for *M. xanthus* cells (118a). Polystyrene latex beads that were found to adhere to these cells (72, 91) were used as tools to help identify potential subcellular motility elements. These spheres were observed to move from one cell pole to the other at speeds similar to the normal gliding speed of a cell. These events were

independent of whether cells were in suspension or were attached to a surface (72). Bead movements could also stop and then resume in the opposite direction before they had reached the cell end. One particularly interesting observation was that multiple beads on the cell surface could move independently of each other. While one bead could be seen moving along the cell body, a second bead on the same cell could stop while a third could move in the opposite direction to the first bead. The speed of bead movement along the cell was independent of bead diameter, which ranged from 0.1 to 1.3 μm . Depletion of oxygen resulted in cessation of both gliding movements and movements of beads on cells, although, interestingly, attached spheres did not exhibit any noticeable Brownian motion. From these observations, a model of gliding for *Cytophaga* strain U67, in which adhesion sites in the outer membrane, which attach to the surface (or to polystyrene beads), are moved in the outer membrane on tracks that are fixed to the rigid cell wall, was proposed (72).

More recently, interference reflection microscopy was used to examine cell-substratum contact during gliding movement in *Cytophaga* strain U67. The entire length of the cell body was rarely seen in contact with the substratum (42). The observed cell-substratum sites were variable and moved relative to the glass substratum. Surface-exposed proteins that form physical contact with a solid substratum were reported after their identification by using substratum-immobilized ^{125}I iodide (21). This set of currently uncharacterized proteins may contain those that mediate gliding-associated cell-substratum adhesion. *Cytophaga* strain U67 shows some degree of curvature in cell shape and was observed in this study to rotate during movement (42). The rotation of *Cytophaga* strain U67 cells around the long axis was sinistral when gliding on a glass surface, and a pitch of the helix about $79^\circ \pm 3^\circ$ for every 8.3 μm of translational gliding movement was observed (42). Surfactants were shown to inhibit swarming and gliding (20).

In *F. johnsoniae*, sulfonolipids were detected as an unusual component of the cell membrane (1). The role of these sulfonolipids was speculated to be in presenting specific polysaccharides to the outer cell surface (41, 44). An uncharacterized mutant defective in sulfonolipid formation was unable to glide or to move polystyrene beads along the cell body. In addition, the mutant was insensitive to phage infection (45). When the sulfonolipid precursor cysteate was provided to the mutant, gliding was rapidly restored. However, bead movement and phage sensitivity took longer to be restored, suggesting that the cell surface features required for bead movement and phage sensitivity are different from those required for gliding (45). A causal relationship between phage sensitivity and bead movement, on the one hand, and gliding motility, on the other, was considered unlikely (43, 45). Recently, negative chemotaxis in *F. johnsoniae* in response to the repellents H_2O_2 and OCl^- , and *N*-chlorotaurine was reported (74).

Many motility mutants of *F. johnsoniae* that are defective in colony swarming have been isolated (25). One subclass of these mutants were nonmotile ("truly nonmotile") in wet-mount preparations and exhibited other pleiotropic phenotypes such as defects in chitin digestion, phage absorption, and cell adherence (25, 135). However, research on these and other *F. johnsoniae* mutants was hampered by the absence of a genetic system to facilitate further molecular analyses. A breakthrough came in 1996, when McBride and Kempf reported successful mutagenesis of *F. johnsoniae* by using *Bacteroides* transposon Tn4351 (85). A plasmid, based on the cryptic plasmid pCP1 (isolated from the closely related *F. psychrophilus*), that stably replicates in *F. johnsoniae* was developed. This plasmid served as the basis for constructing a genomic library of this micro-

organism. Using this library, a single open reading frame, named *gldA*, was identified and was found to be sufficient to complement the motility defect of 4 of 61 independently isolated nonmotile mutants (2). The predicted amino acid sequence of GldA shows strong homology to ABC transport proteins. GldB and GldD are predicted to be membrane proteins. Other mutations rendering cells unable to glide map to genes encoding proteins involved in cell surface lipopolysaccharide synthesis (85a). Further use of these tools for genetic investigations of gliding in *F. johnsoniae* will undoubtedly uncover new insights in the gliding mechanism of this bacterium. Comparing the molecular components identified in *F. johnsoniae* with those in *M. xanthus* will significantly enhance our understanding of this translocation process and its diversity.

GLIDING MOTILITY IN *FLEXIBACTER POLYMORPHUS*

In contrast to the above gliding bacteria, *Flexibacter polymorphus* is a filamentous bacterium that forms multicellular filaments which are enclosed by a common outer membrane. Extensive studies of gliding movements of *F. polymorphus* filaments were conducted by Ridgway and Lewin (100). Similar to *M. xanthus* and *Cytophaga* strain U67, *F. polymorphus* filaments start to glide immediately once in contact with a surface (100). When suspended in liquid medium and when forming contact only with each other, *F. polymorphus* filaments were observed to glide relative to each other (100). Gliding of filaments on an agar surface was accompanied by a sinistral rotation of the cell body. The gliding speed of a filament is approximately 12 $\mu\text{m/s}$ and is independent of the filament length. *F. polymorphus* filaments were observed to spin or pivot around the long axis of the cell when only one cell end was attached to the substratum. By using dextran to manipulate the viscosity of the liquid medium, it was found that the gliding speed was inversely proportional to the viscosity, suggesting that the gliding motor operates at constant torque (100). Filaments exhibited a tactile response and reversed the direction of movement by gliding backward upon contact with an object. The frequency of reversal was observed to be inversely correlated with the filament length. Polystyrene beads were observed to move across the entire cell length at approximately the same speed as the filaments glide. Bead movement occurred in a more irregular fashion than did analogous movements in *Cytophaga* strain U67. Small beads tended to move in a more helical fashion, whereas particles of $>0.3 \mu\text{m}$ were translocated less uniformly and did not circumvent the filament. Movement of multiple beads on a single filament seemed to be independent of each other. Bead movement was also observed on nongliding filaments and filaments suspended in liquid. Because bead movement was observed in nongliding filaments, it was concluded that bead movement may not necessarily be coupled to gliding movements. Extracellular fibrils that originate laterally from the cell body are involved in cell-substratum adhesion. The chemical composition of the *F. polymorphus* fibrils and associated exopolysaccharide is unknown, and these fibrils may very well be different from those observed in *M. xanthus*. The energy to power the gliding machinery is believed to be derived from the electrochemical proton potential (98). No genetic studies have been reported for *F. polymorphus*.

MOTILITY IN CYANOBACTERIA

As indicated above, "gliding" is an operational definition, and considering the diversity of microorganisms capable of this type of surface translocation, different mechanisms may operate in different microbes. Two interesting observations on

motility in cyanobacteria are important to mention when considering non-flagellum-based motility: swimming of nonflagellated *Synechococcus*, and slime extrusion in gliding of *Phormidium unicum* and *Anabena variabilis*. In 1985, Waterbury et al. reported the isolation of several strains of the unicellular cyanobacterium *Synechococcus* that are capable of rapid swimming motility in the absence of flagella (128). Subsequent studies showed that their motility is dependent on a sodium gradient as the energy source (134). Furthermore, Ca^{2+} was found to be required for motility, and a highly abundant Ca^{2+} binding protein that is essential for motility was identified in the cell surface (19, 93). Self-electrophoresis was ruled out as a mechanism for this very interesting mode of movement (92). Based on theoretical considerations, a mechanism of traveling (longitudinal) surface waves was considered instead (35). A similar mechanism of wave propagation along the cell surface also presents an attractive model for single-cell gliding motility. Most behavioral observations made on gliding microorganisms (single-cell studies, bead movement, etc.), as well as the ultrastructural findings in *M. xanthus*, are consistent with such mechanism. However, gliding microorganisms have to be able to adhere reversibly to the substratum. Notably, *M. xanthus*, *F. johnsoniae*, *Cytophaga* strain U67, and *F. polymorphus* have not been reported to move by swimming. Research on this unusual mode of swimming in unicellular *Synechococcus* may provide unexpected insights into the diversity of bacterial translocation mechanisms that may affect our thinking on gliding motility as well.

Recently, the slime extrusion hypothesis of Ridgway (99) was revived by reports by Hoiczky and Baumeister while studying the filamentous gliding cyanobacteria *P. unicum* and *A. variabilis* (59). Using electron microscopy studies, these authors reported finding "junctional pore complexes" at the cross wall or septa of the filaments. These structures show some similarity to the type III secretion system apparatus in *S. typhimurium* (71). The junctional pore complexes seem to be involved in slime secretion in these cyanobacteria. As in many other gliding microorganisms, slime production is often associated with gliding. It was speculated that directional slime extrusion through the junctional pore complexes may be the motor for gliding in these cyanobacteria (59). However, no physiological evidence supports this hypothesis, and it is not clear whether slime formation is the result or cause of gliding motility.

CONCLUSIONS

The mechanism of gliding motility in prokaryotes is one of the few remaining enigmas in microbiology. Research in the past years has provided a wealth of information and revealed that several mechanistically unrelated gliding motors (pilus-dependent versus pilus-independent gliding) are involved in gliding, even in a single microorganism. Although the pilus-independent mechanisms may have different molecular architecture in the microorganisms described here, certain strikingly similar features have been observed in all the microbes. Considering the genetic, biochemical, and high-resolution optical tools available, it seems certain that in the near future we will begin to understand the molecular mechanics of single-cell gliding (pilus-independent gliding) and type IV pilus-dependent gliding.

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